

Introduction

Goal

study topological objects up to some equivalence relation

homeomorphism too strong

$$A \not\cong_0 O$$

but A can deform into O

want to ~~study~~ classify things up to deformation \rightsquigarrow homotopy

tool



want

- ① computable
- ② reflect ~~properties~~ structures
- ③ invariant wrt homotopy

Ex

① # of components

② genus.

(connected orientable surfaces)



Some definitions

convention

X, Y, Z : topological spaces.

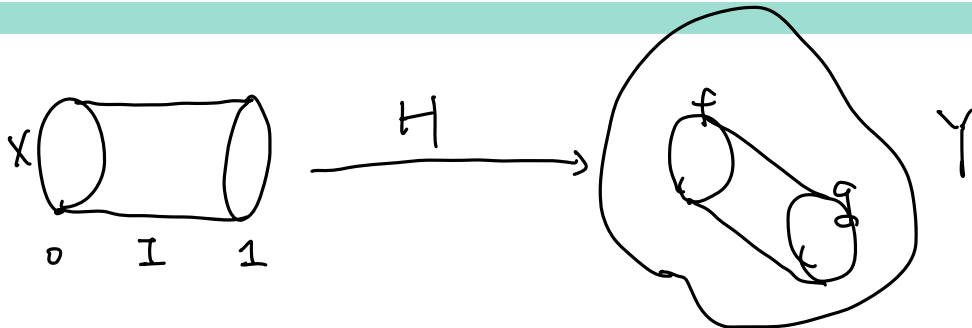
all maps are continuous maps.

Def (homotopic). (write $f \simeq g$)

$f, g: X \rightarrow Y$ are homotopic if

$$\exists H: X \times I \rightarrow Y \quad \text{s.t.} \quad \begin{aligned} H|_{X \times \{0\}} &= f \\ H|_{X \times \{1\}} &= g \end{aligned}$$

$I = [0, 1]$



think of H as a family of maps from X to Y parametrized over I .

for each $t \in [0, 1] \mapsto h_t: X \rightarrow Y$

prop \simeq defines an equivalence relation on the set of maps from X to Y .

Def ① $f: X \rightarrow Y$ is a homotopy equivalence

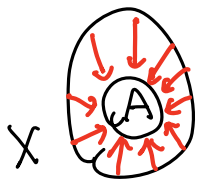
$$\text{if } \exists g: Y \rightarrow X \quad \text{s.t.} \quad \begin{aligned} f \circ g &\simeq \text{id}_Y \\ g \circ f &\simeq \text{id}_X \end{aligned}$$

② when $\exists f: X \rightarrow Y$ homotopy equivalence, we say X homotopy equivalent to Y .

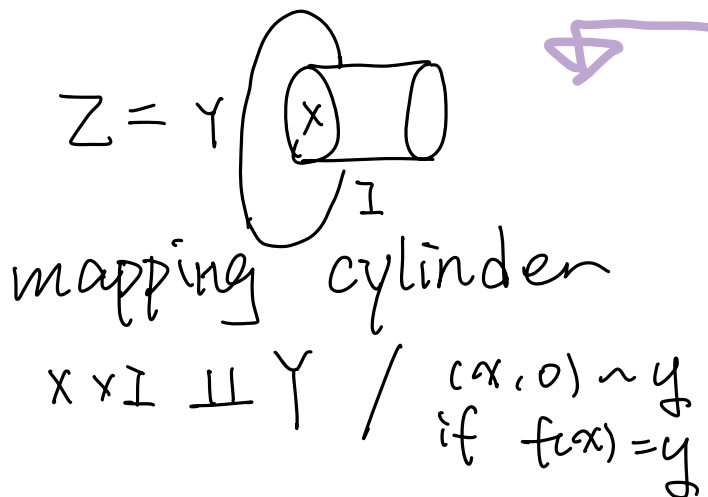
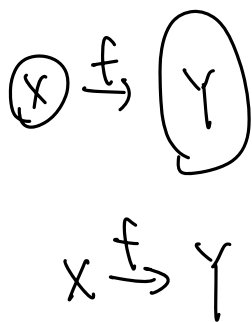
Compare definition with geometric intuition

Fact $X \xrightarrow{f} Y$ homotopy equivalence
 $\Leftrightarrow X$ & Y are homeomorphic to a strong deformation retract of another space.

Def (strong deformation retract)
 $F: X \times I \rightarrow X$ is a strong def. retract from X to $\text{Im}(F_1)$ if.
 $F_0 = \text{id}_X$ & $F|_{A \times I} = \text{id}_A$. !A



points in A : in same position
 points outside A : deformed to A



$Z \xrightarrow[\text{retract}]{\text{strong deformation}} Y$: smash $X \times I$ to $X \times \{0\}$

$Z \xrightarrow[\text{retract}]{\text{strong deformation}} X$: use homotopy equivalence
(exercise)

Based world

Based spaces: X with a pre-assigned base pt
 $x_0 : * \rightarrow X$, write (X, x_0)

maps of based spaces: preserves base pt

$(X, x_0) \xrightarrow{f} (Y, y_0) \quad \therefore f : X \rightarrow Y$ with
 $f(x_0) = y_0$.

Def (fundamental groups).

The **fundamental group** of a based space (X, x_0) , denoted by $\pi_1(X, x_0)$, is

① underlying set :
homotopy equivalence classes of
based maps $(S^1, *) \rightarrow (X, x_0)$.
↳ circle

think of a map $(S^1, *) \rightarrow (X, x_0)$ as a loop.

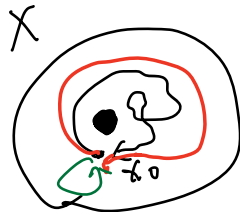
$$S^1 = \mathbb{I} / \{0\} \sim \{1\} \quad \bullet_x$$

$$\bullet (S^1, *) = (\mathbb{I} / \sim) \xrightarrow{p} (X, x_0)$$



$$\bullet p: \mathbb{I} \rightarrow X \text{ with}$$

$$p(0) = p(1) = x_0$$



$$\hookrightarrow \neq \circlearrowleft \simeq \circlearrowleft$$

② group structure

a) addition b) identity c) inverse

a)



$$[p_1] + [p_2] = \text{concatenation} = t \mapsto \begin{cases} p_1(2t) & t \in [0, 1/2] \\ p_2(2t-1) & t \in [1/2, 1] \end{cases}$$

need to prove (associativity)

$$([p_1] + [p_2]) + [p_3] = [p_1] + ([p_2] + [p_3])$$



b) identity

$C_{x_0} = t \mapsto x_0$
constant path on x_0

c) inverse



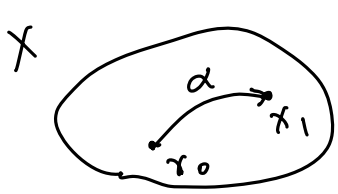
need to show

$$t \mapsto p(1-t)$$

exercise

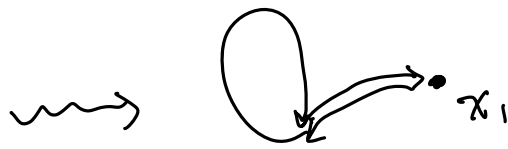
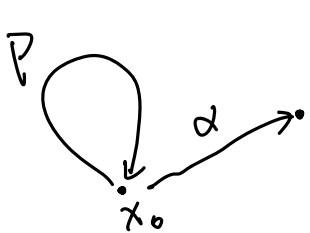
- $[p] + [p]^{-1} = [c_{x_0}]$
- $[c_{x_0}] + [p] = [p]$
- $[p] + [c_{x_0}] = [p]$
- independence of representatives

Base point (in)dependence



suppose \exists path $x_0 \xrightarrow{\alpha} x_1$

\rightsquigarrow α gives an assignment



$$p \in \pi_1(X, x_0)$$

$$\rightsquigarrow \alpha p \alpha^{-1} \in \pi_1(X, x_1)$$

Claim: this defines a grp homomorphism

$$\gamma(\alpha) : \pi_1(X, x_0) \rightarrow \pi_1(X, x_1)$$

$$\gamma(\alpha^{-1}) : \pi_1(X, x_1) \rightarrow \pi_1(X, x_0)$$

Claim: $\gamma(\alpha)$ inverse to $\gamma(\alpha^{-1}) \rightsquigarrow \pi_1(X, x_0) \cong \pi_1(X, x_1)$

Q: $\begin{matrix} x_0 & \xrightarrow{\alpha} & x_1 \\ & \searrow \beta & \end{matrix}$ is $r(\alpha) \stackrel{?}{=} r(\beta)$. ?

A: If $\pi_1(X, x_0)$ abelian, yes. exercise

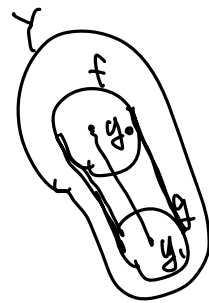
homotopy invariance

prop $f \simeq g: X \rightarrow Y$ $\begin{matrix} f(x_0) = y_0 \\ g(x_0) = y_1 \end{matrix}$

then $\begin{matrix} f_* \swarrow & & \searrow g_* \\ \pi_1(Y, y_0) & \xrightarrow{r(\alpha)} & \pi_1(Y, y_1) \end{matrix}$
is commutative.

Here

- $\alpha = \text{path } [x_0, x_1] = y_0 \xrightarrow{\text{path}} y_1$



- $f_*: [p] \in \pi_1(X, x_0)$

$$\downarrow$$

$$[f \circ p] \in \pi_1(Y, y_0)$$

$$f: X \rightarrow Y$$

$$[p]: S^1 \rightarrow X \in \pi_1(X)$$

$$f \circ p: S^1 \rightarrow X \rightarrow Y \in \pi_1(Y)$$

similar for g_* .

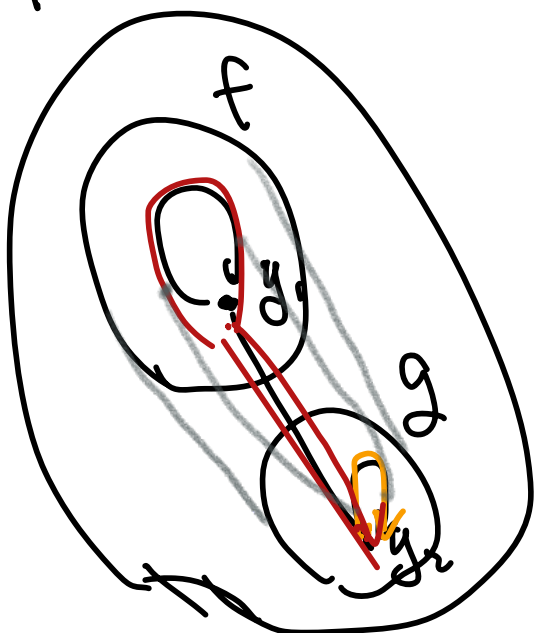
exercise: check well-definedness of f_*, g_*

pf want to show $r(\alpha) f_* = g_*$

$p: I \rightarrow X$ with $p(0) = p(1) = x_0$

$g_*(p) = \underline{g \circ p} : I \xrightarrow{p} X \xrightarrow{g} Y$

$r(\alpha) f_*(p) = r(\alpha) f \circ p = \underline{\alpha \circ f \circ p \circ \alpha^{-1}}$



$H: X \times I \rightarrow Y$

$p: I \rightarrow X$

$H \circ (p \times I):$

$I \times I \xrightarrow{p \times I} X \times I \xrightarrow{H} Y$

$f(x_0) = y_0$

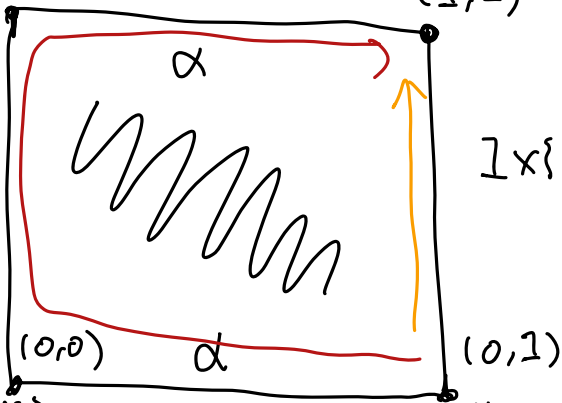
$\{1\} \times I$

$g(x_0) = y_1$

$\{1, 1\}$

$I \times \{0\}$

$H \circ p = f \circ p$



$I \times \{1\}$

$H \circ p = g \circ p$

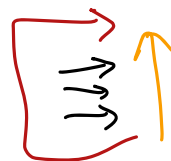
$\rightarrow Y$

$f(x_0)$
 y_0

$\{0\} \times I$

y_1

\exists a homotopy



$g \circ p \sim \alpha \circ f \circ p \circ \alpha^{-1}$

Cor $X \xrightarrow{f} Y$ homotopy equivalence

Then $f_*: \pi_1(X) \rightarrow \pi_1(Y)$ is isomorphism.

sketch. ① $\exists g$ s.t. $g \circ f \simeq \text{id}_X$
use $f \circ g \simeq \text{id}_Y$

$$\text{② } (\text{id}_X)_* = \text{id}_{\pi_1(X)}$$

$$(\text{id}_Y)_* = \text{id}_{\pi_1(Y)}$$

Computation

Def. If $X \simeq *$, we say X is contractible.

Ex: \mathbb{R}^1

①. Using Cor $\Rightarrow \pi_1(\mathbb{R}) = \text{trivial grp.}$

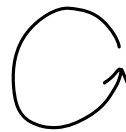
$$\text{② } \pi_1(S^1) = \mathbb{Z}$$

1) identify S^1 with unit sphere $\subseteq \mathbb{C}$

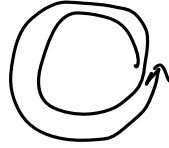
$$t \mapsto e^{2\pi i n t}$$

$$[0, 1] \rightarrow S^1 \subseteq \mathbb{C}$$

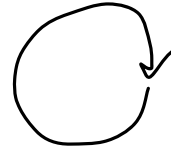
$$n = 1$$



$$n = 2$$

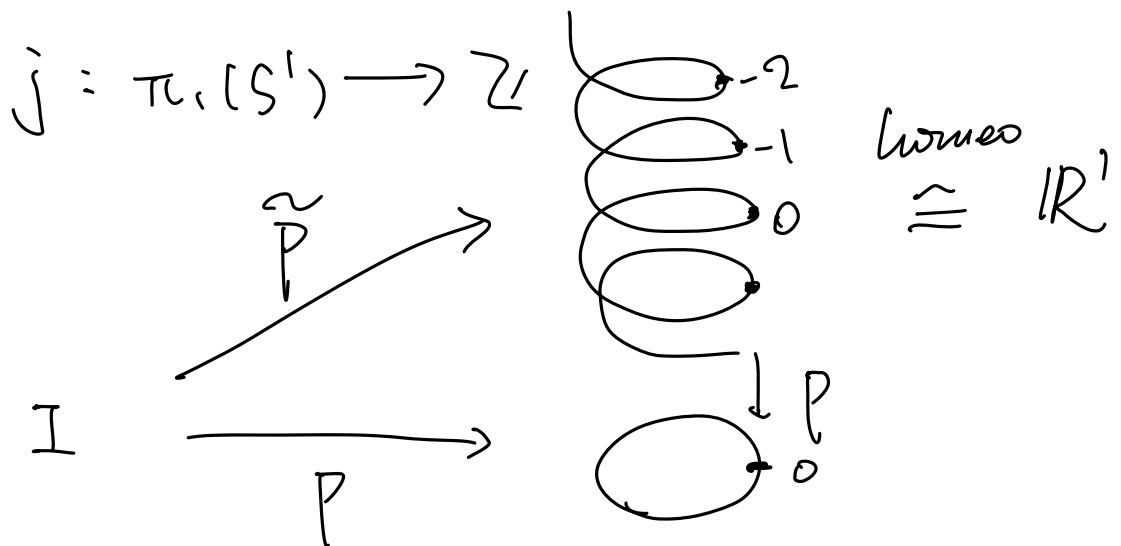


$$n = -1$$



$$\begin{aligned} \tilde{c}: \mathbb{Z} &\longrightarrow \pi_1(S^1) \\ n &\longmapsto t \longmapsto e^{2\pi i n t} \end{aligned}$$

Claim: \tilde{c} is a homomorphism



Claim: given $p: I \rightarrow S^1$ with $p(0) = p(1) = 0$

\exists : lift $\tilde{p}: I \rightarrow \mathbb{R}^1$ with $\tilde{p}(0) = 0, \tilde{p}(1) = n$ for some integer n

$$j : P \mapsto \tilde{P}(1) = \text{deg}$$

Claim: 1) j is well-defined

$$2) j \circ i = \text{id}_Z \Rightarrow \begin{matrix} i \\ j \end{matrix} \begin{matrix} \text{inj} \\ \text{surj} \end{matrix}$$

$$3) j \text{ is inj} \Rightarrow i \text{ is bij}$$

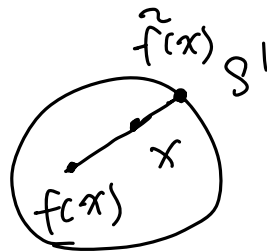
Application

⊙ Brouwer fixed pt th'm

Any continuous map $D^2 \rightarrow D^2$ has a fixed pt.

pf suppose $f: D^2 \rightarrow D^2$ with no fixed pt.

$$\tilde{f}: x \mapsto$$



get $\tilde{f}: D^2 \rightarrow S^1$ with

$$\tilde{f}|_{S^1} = \text{id}_{S^1}$$

$$\text{id}_{S^1} = S^1 \xrightarrow{\text{inclusion}} D^2 \xrightarrow{\tilde{f}} S^1$$

Apply π_1

$$\text{id} = (\text{id}_{S'})_* = \pi_*(S') \xrightarrow{(\text{inc})_*} \pi_*(\mathbb{D}^2) \xrightarrow{f_*} \pi_*(S')$$

$$\mathbb{Z} \longrightarrow 0 \longrightarrow \mathbb{Z}$$

contradiction!

② fundamental thm of alg

$$f(x) = x^n + c_1 x^{n-1} + c_2 x^{n-2} + \dots + c_n$$

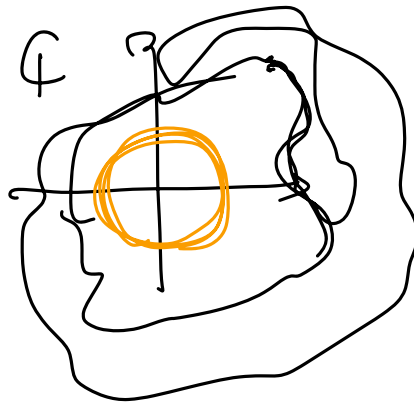
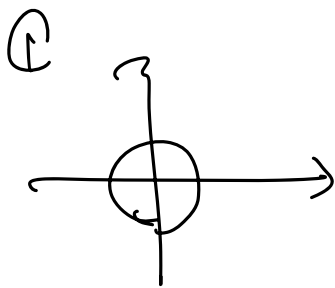
then $f(x)$ has n roots in \mathbb{C} .
(consider multiplicity)

pf only need to show
 $f(x)$ has 1 root.

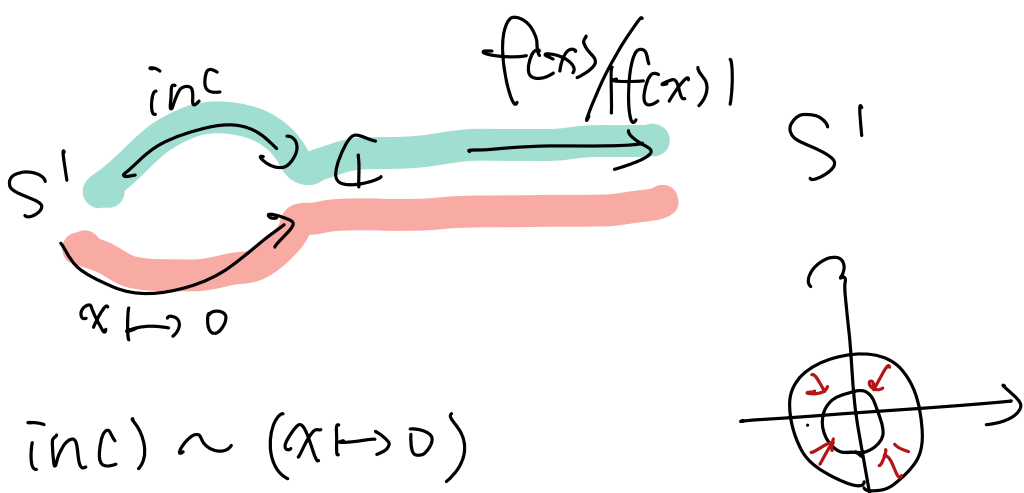
Suppose $f(x)$ doesn't have any roots.

$$S' \hookrightarrow \mathbb{C} \xrightarrow{f(x)/|f(x)|} S' \subseteq \mathbb{C}$$

$$\in \pi_*(S') = \mathbb{Z}$$

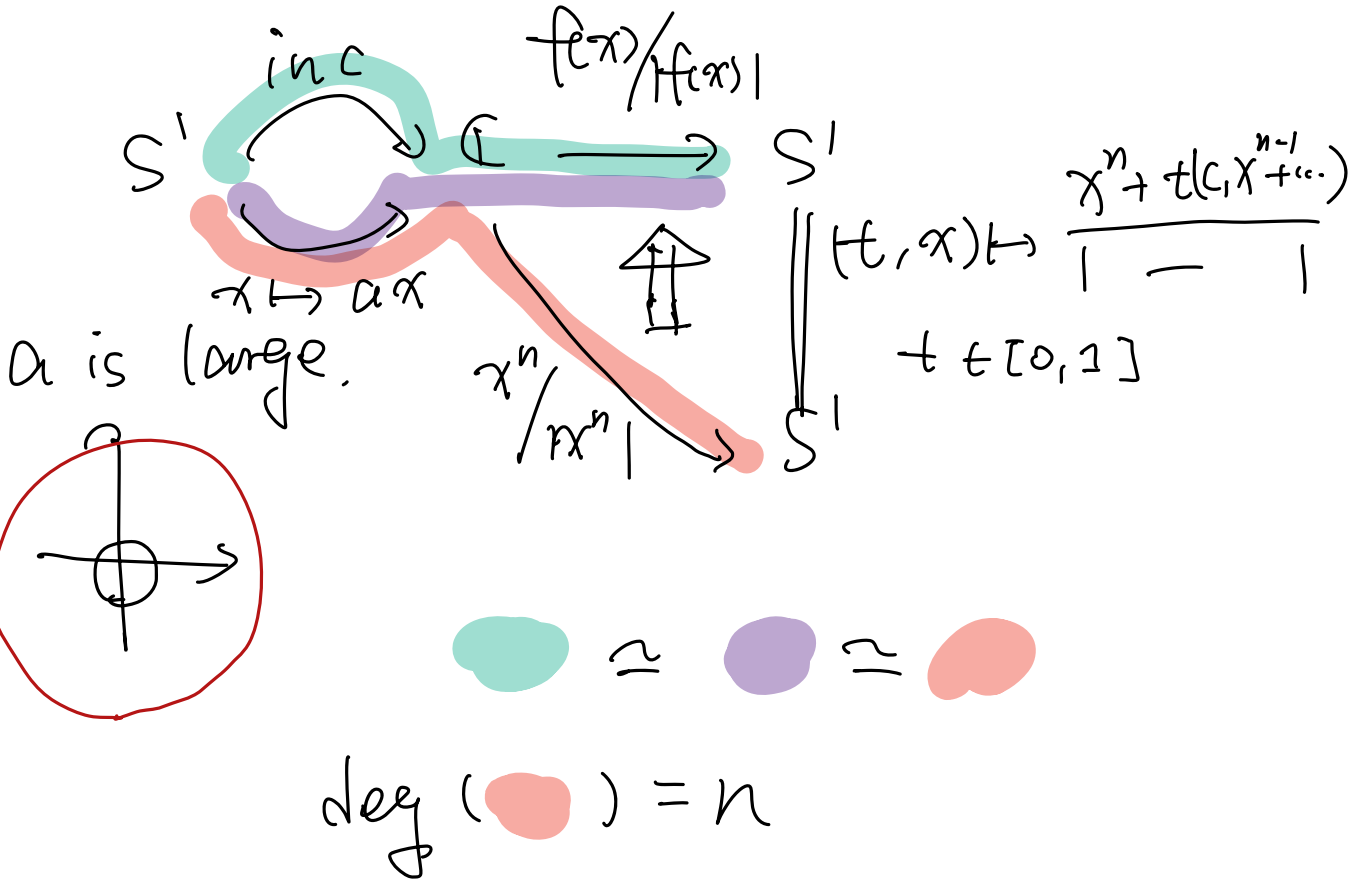


①.



$\Rightarrow [\text{green path}] = [\text{red path}] \in \pi_1(S^1)$
 $\text{deg} = 0$

②



② contradicts ①

Lemma

$$\pi_1(X \times Y) = \pi_1(X) \times \pi_1(Y)$$

Sketch

$$p: I \rightarrow X \times Y$$

$$p_x: I \rightarrow X \times Y \rightarrow X$$

$$p_y: I \rightarrow X \times Y \rightarrow Y$$

$$[p] \mapsto ([p_x], [p_y])$$

Exercise Show \uparrow is grp isomorphism.

$$\text{Ex } \pi_1(T^2) = \pi_1(S^1 \times S^1) = \mathbb{Z} \times \mathbb{Z}$$



$$Q: X = U \vee V$$

know $\pi_1(U)$

$\pi_1(V)$

$\pi_1(U \cap V)$

induced maps

How to compute $\pi_1(X)$?

A: van Kampen thm

Some category theory

Def (Category).

a category \mathcal{C} is the following ^{data}

① $\text{obj} : \text{ob } \mathcal{C}$.

② $a, b \in \text{ob } \mathcal{C}$, morph $\mathcal{C}(a, b)$
with $\text{id}_a \in \mathcal{C}(a, a)$

③ composition that is associative

$$\mathcal{C}(a, b) \times \mathcal{C}(b, c) \xrightarrow{\circ} \mathcal{C}(a, c)$$

associative:

$$(f \circ g) \circ h = f \circ (g \circ h)$$

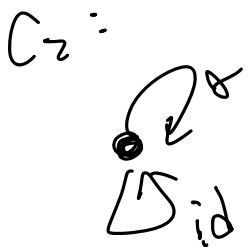
Ex : ① Set, Top, ^{pointed top spaces} Top*, Grp

②. G : group

\mathcal{C}_G : the cat associated to G .

obj : $\bullet \rightarrow g$

morph : $\mathcal{C}_G(\bullet, \bullet) = G$



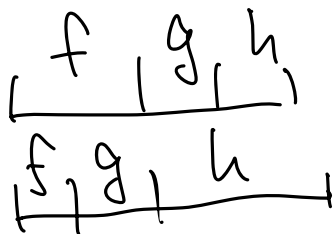
②. fundamental groupoid for X

$\pi(X)$

Obj: points in X

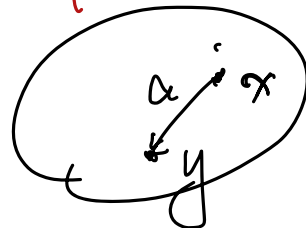
morph: $\pi(X)(x, y)$

= $\{\text{paths } x \rightarrow y\} / \text{homotopy}$



necessary for composition

$$\begin{array}{ccc} x & \xrightarrow{a} & y \\ y & \xrightarrow{a^{-1}} & x \end{array}$$



groupoid: \checkmark

each morphism has an inverse.

Functors

Def: a functor $F: \mathcal{C} \rightarrow \mathcal{D}$ is

① a map $F: \text{ob } \mathcal{C} \rightarrow \text{ob } \mathcal{D}$

② $F: \mathcal{C}(a, b) \rightarrow \mathcal{D}(F(a), F(b))$

$$F(\text{id}_a) = \text{id}_{F(a)}$$

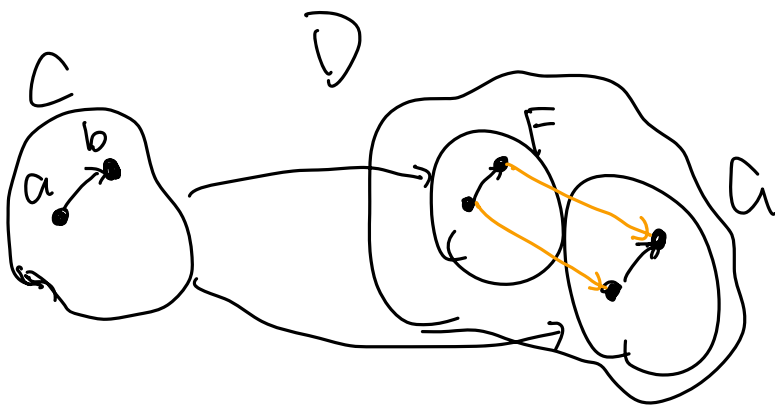
respect composition

$$F(f) \circ F(g) = F(f \circ g)$$

Def (natural transformation). $F, G: \mathcal{C} \rightarrow \mathcal{D}$

a natural transformation $\eta: F \Rightarrow G$ is the following:
 for $\forall a \in \mathcal{C}$, there is a morph $\eta_a: F(a) \rightarrow G(a) \in \mathcal{D}$, s.t.

$$\begin{array}{ccc}
 F(a) & \xrightarrow{\eta_a} & G(a) \\
 F(f) \downarrow & \curvearrowright & \downarrow G(f) \\
 F(b) & \xrightarrow{\eta_b} & G(b)
 \end{array}$$



$$I: \begin{matrix} \bullet \\ \downarrow \\ 0 \end{matrix} \rightarrow \begin{matrix} \bullet \\ \downarrow \\ 1 \end{matrix}$$

claim a natural transf

some
data

$$H: \mathcal{C} \times I \rightarrow \mathcal{D}$$

$$\text{s.t. } H|_0 = F$$

$$H|_1 = G$$

Def

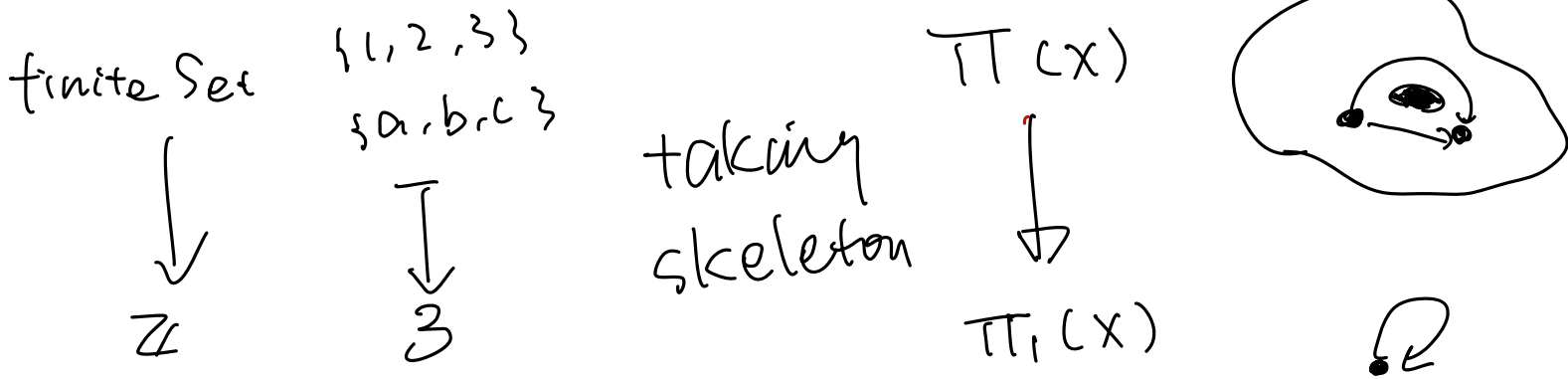
(natural isomorphism).

natural transformation + each η_a is an isomorphism/equivalence.

a morphism is an iso/eq if it is invertible.

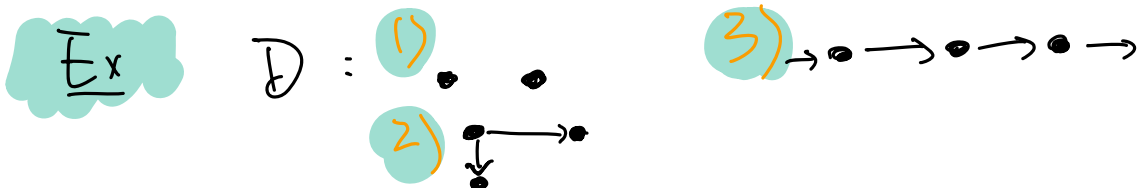
Space	cat.
conti map	functor
homotopy	natural transformation
$X \xrightarrow{f} Y$ homotopy eq if.	$\mathcal{C} \xrightarrow{F} \mathcal{D}$ equivalence if
$\exists g: Y \rightarrow X$ s.t. $f \circ g \simeq id$	$\exists G: \mathcal{D} \rightarrow \mathcal{C}$ s.t.
$g \circ f \simeq id$	$G \circ F \simeq id$
	$F \circ G \simeq id$
	natural isomorphism

Prop X is path connected.
 Then $\pi(X)$ & $\pi_1(X)$ viewed as a cat
 are equivalent.

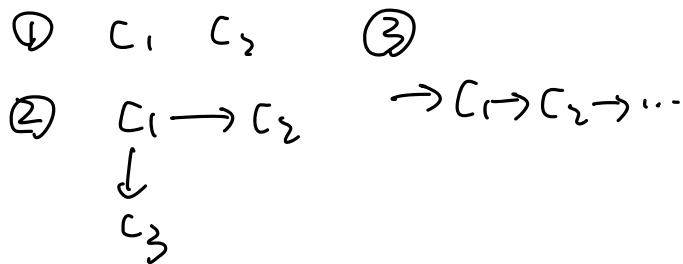


colimit

\mathcal{D} : (small) category



$F: \mathcal{D} \rightarrow \mathcal{C}$
is a diagram in \mathcal{C} .



Def (colimit)

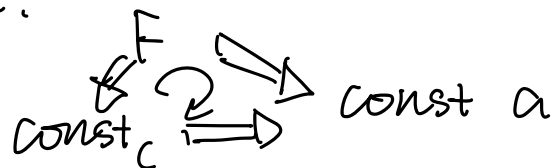
$\text{colim } F$ is

- ① $c \in \mathcal{C}$
- ② $F \Rightarrow \text{const } c$

satisfying for $\forall F \Rightarrow \text{const } a$ $(\mathcal{D} \rightarrow \mathcal{C})$
 $(d \mapsto c)$

$\exists ! c \rightarrow a$ s.t.

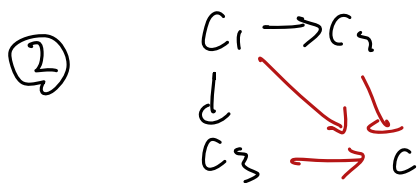
(universal property)



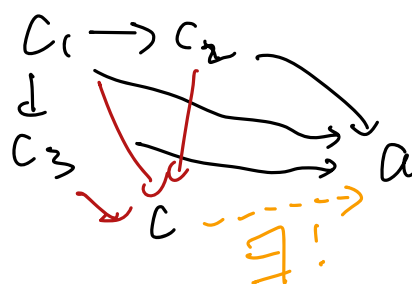
Ex

②) colim $c_1 \rightarrow c_2$
 \downarrow
 c_3

① a obj $c \in \mathcal{C}$.

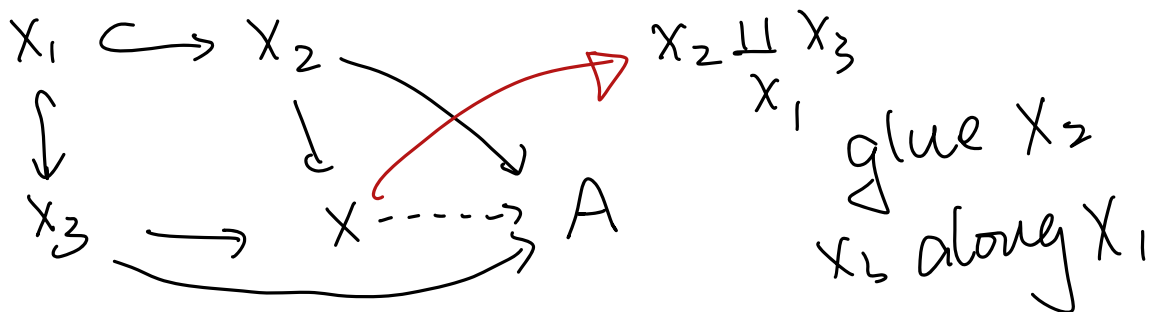


satisfying
for $\forall a$ with



(more on this) example

\mathcal{C} is Top



Thm (van Kampen)

X path connected, choose base pt x_0

\mathcal{O} : a cover of X , such that \mathcal{O} is closed under taking intersection of finitely many elements in \mathcal{O} \rightarrow meaning


$$\text{i.e. } \mathcal{O} = \{U_i\}, \bigcap_{i \in I} U_i \in \mathcal{O} \text{ for } |I| < \infty$$

X & all U_i are path connected
view \mathcal{O} as a category \rightarrow in this way

$$\text{ob } \mathcal{O} : \{U \in \mathcal{O}\} \rightarrow U \hookrightarrow U'$$

$$\text{morph} : \mathcal{O}(U, U') = \begin{cases} \rightarrow & U \hookrightarrow U' \\ \emptyset & U \not\hookrightarrow U' \end{cases}$$

$\mathcal{O} : U_1, U_2, U_1 \cap U_2$ \rightarrow this is an example



consider the functor $F: \mathcal{O} \rightarrow \text{groupoids}$
 $U_i \rightarrow \pi(U_i)$

$$\text{Then } \pi(X) = \text{colim } F$$

$$(\text{or written as } \text{colim}_{\mathcal{O}} \pi(U_i))$$

⌘ this version of van Kampen

↪ translate π to π , using $\pi(x)$

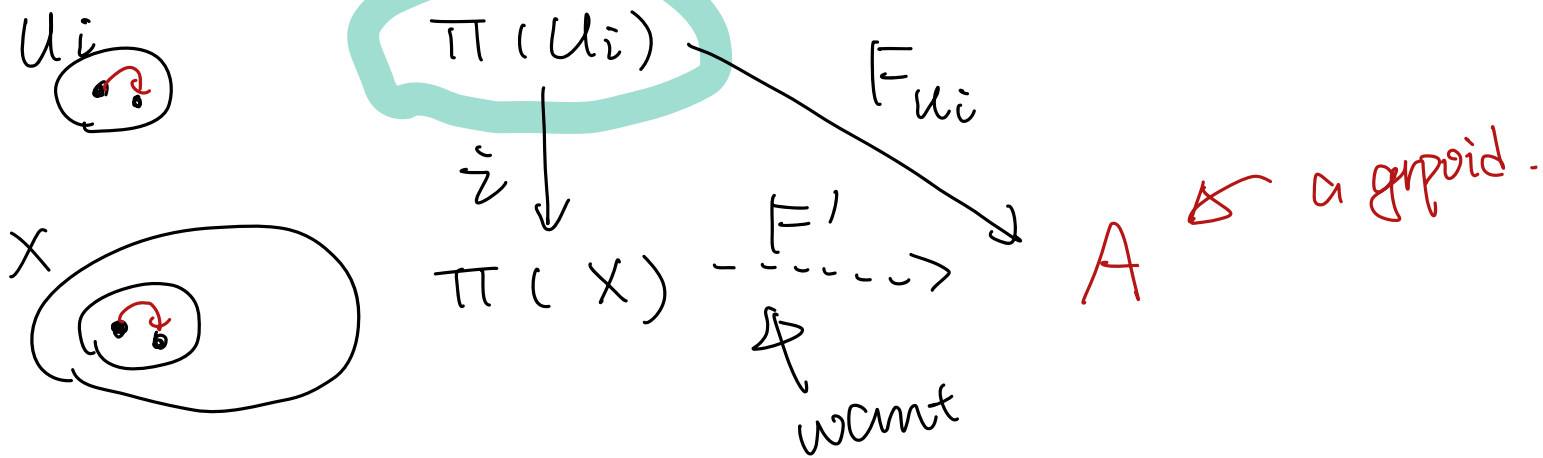
in the textbook
Chap 2, p18

↪ write out formulas for
colim in grp.

Think about what
colimits are in cat of grps.

↪ Hatcher
wikipedia
version

Pf: to verify the universal property.



on obj

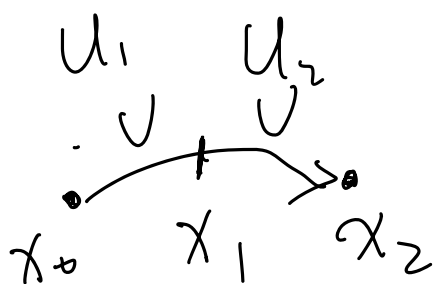
$x \in X$ also in U



on morph.

① If a path in X is entirely in some U ✓

② Otherwise, subdivide.



By ① we know how

$$x_0 \rightarrow x_1 \&$$

$$x_1 \rightarrow x_2$$

are mapped to A .

Define $F'(x_0 \rightarrow x_2)$

$$:= F_{U_2}(x_1 \rightarrow x_2) \circ F_{U_1}(x_0 \rightarrow x_1)$$

Check ① everything well defined

② uniqueness of F is clear.